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Global Self-Localization For Autonomous Mobile Robots Using Region- And Feature-Based Neural Network - Industrial Electronics, Control, And Instrumentation, 1995., Proceedings Of The 1995 IEEE Mar 2th, 2024

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1. ANSI/RIA R15.06-2012 (ISO 10218-1:2011) The first is ANSI/RIA R15.06-2012: American National Standard For Industrial Robots And Robot Systems- Safety Requirements (revision Of ANSI/RIA R15.06-1999)1. R15.06 Primarily Covers Some Of The Basic Requirements For AMRs. A Lot Has Mar 3th, 2024

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