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2 DOF ROBOT Www.makeblock.cc Lab Kit Ultimate Kit V1.1. Part List Beam

0824-144 Beam 0824-160 Plate 3x6 2x 1x 2x DC Motor-25 Countersunk Screw M3x8  
DC Motor-25 Bracket 2x 6x Headless Screw M3x5 Shaft Connector-4 5x Timing  
Pulley 90T 2x 6x 3x Bracket 3x3 Flange Bearing 4x8x3mm Shaft Collar 4mm 3x  
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Makeblock Constructor I 3D Printer Kit 19 2.4.1 Wiring Four Stepper Motors Step1. Connect The X Motor To The Connector Labeled X. Ensure The Red Cable Is Closest To The Green Screw Terminals On The RAMPS Board (Wire Orders From Left To Right: Red, Blue, Green And Black). Note: If You Don't Wiring By Color Order, The Motor Motion Will Be Incorrect. Feb 10th, 2024

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#define IMU\_SDA\_PIN 21 #define IMU\_SCL\_PIN 22 Using The IMU The IMU On The Shield Is The LSM9DS1, Which Is Connected The The ESP32 Thing To The I2C Port Only. Any Of The Examples From The LSM9DS1 Library Should Jan 13th, 2024

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