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DC Motor-25 Bracket 2x 6x Headless Screw M3×5  
Shaft Connector-4 5x Timing Pulley 90T 2x 6x 3x  
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Based On Makeblock Open Platform, MDrawBot Is A Transformable Drawing Robot Kit That Integrates Mechanics, Electronics, Software, And Art. It Can Be Assembled Into Four Forms: MScara (Cylindrical Coordinates Robotic Arm), MSpider (Wall-Drawing Machine), MEggBot (Egg ... Feb 6th, 2024

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Makeblock Constructor I 3D Printer Kit 19 2.4.1 Wiring Four Stepper Motors Step1. Connect The X Motor To The Connector Labeled X. Ensure The Red Cable Is Closest To The Green Screw Terminals On The RAMPS Board (Wire Orders From Left To Right: Red, Blue, Green And Black). Note: If You Don't Wiring By Color Order, The Motor Motion Will Be Incorrect. Jan 5th, 2024

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```
#define IMU_SDA_PIN 21 #define IMU_SCL_PIN 22
```

Using The IMU The IMU On The Shield Is The LSM9DS1, Which Is Connected The The ESP32 Thing To The I2C Port Only. Any Of The Examples From The LSM9DS1 Library Should Mar 5th, 2024

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