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The Regulation Is Achieved By A PID Controller. Simulink Model Of The Closed Loop Converter Is Shown In Figure 7b. Simulink PID Control Block Is Illustrated In Figure 7c . The Parameters Used For The Closed-loop Simulation Are : $Vi = 12 \ V \ L = 300 \ H \ C \ 14th, \ 2024$

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- 3 Agenda -Day 2 Day 2 10:00 Am -11:00 Pm
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